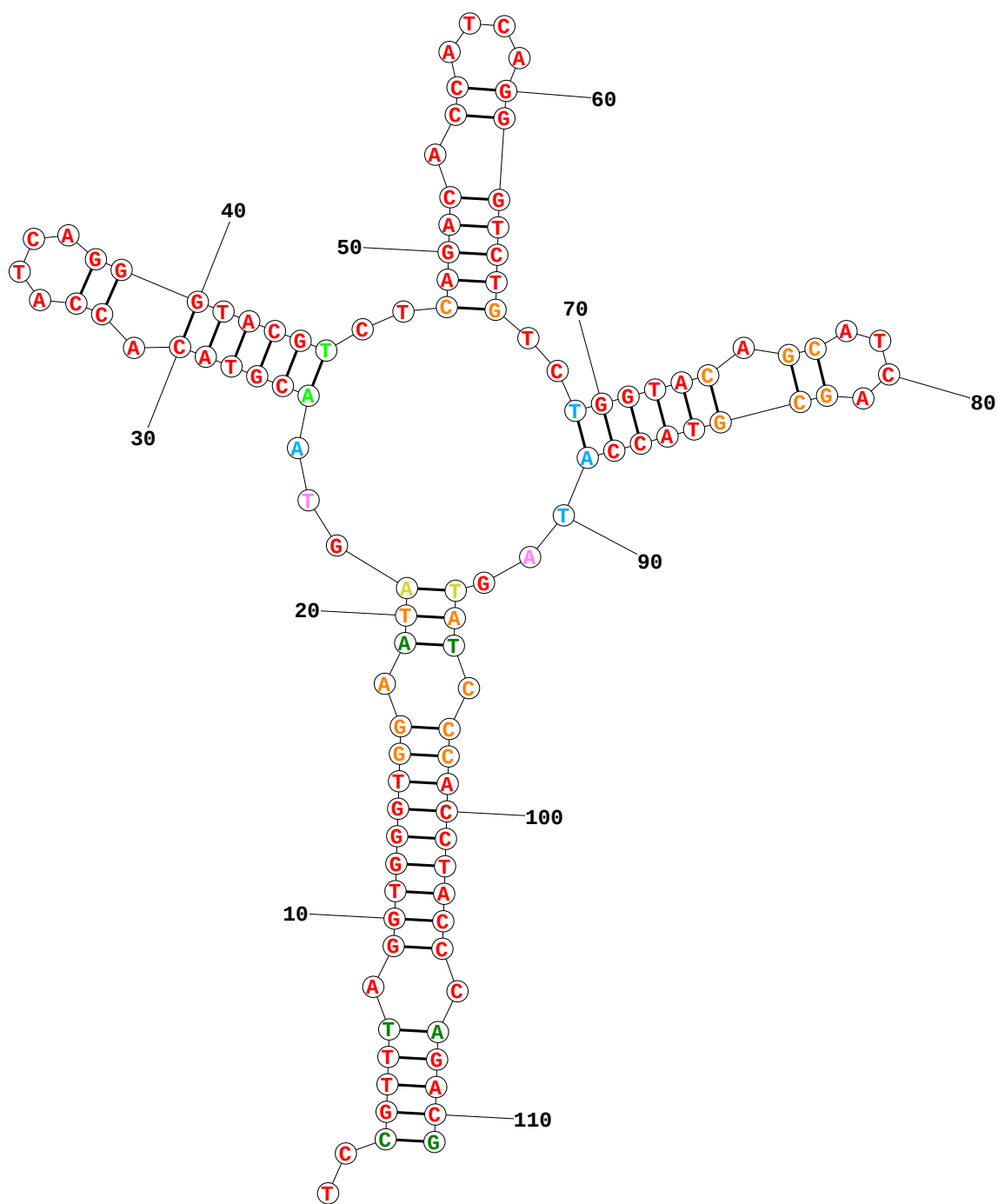




Probability >= 99%
99% > Probability >= 95%
95% > Probability >= 90%
90% > Probability >= 80%
80% > Probability >= 70%
70% > Probability >= 60%
60% > Probability >= 50%
50% > Probability

lidar